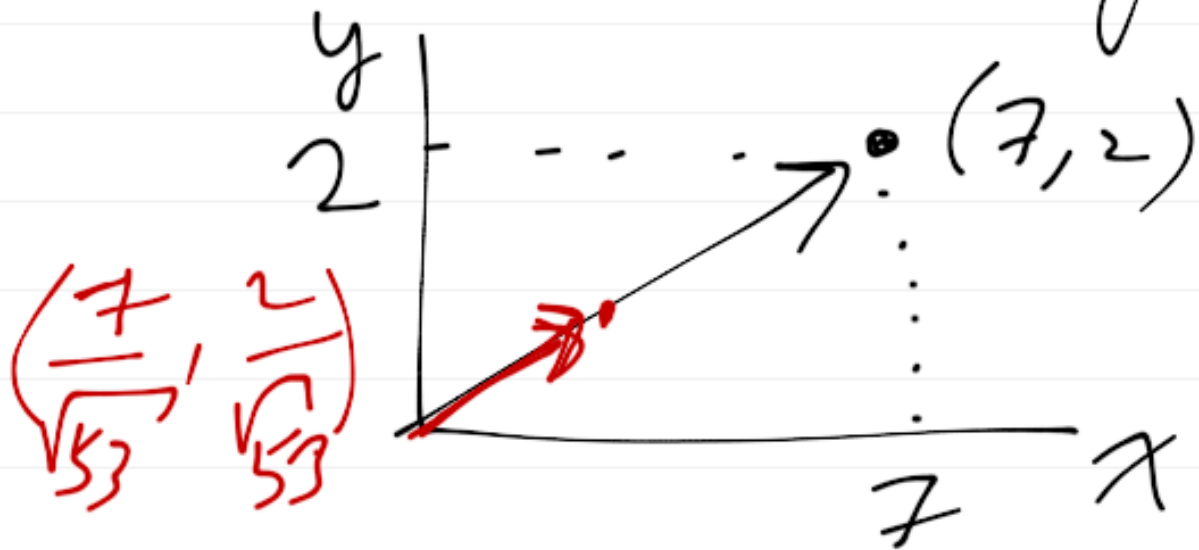


$\text{vec_unit}(\text{vec_t } v1, \text{vec_t } v2)$

// Compute $v2$ (output), a

// Unit Vector in dir of $v1$



$V = (7, 2)$ is a point, a location, with coords $(7, 2)$

Unit vector $\equiv \frac{v}{\|v\|}$ direction

keep in mind "duality" of
vector semantics : position
or direction

Vec_Unit (Vec_t vin, Vec_t vout)

{
vout[0] = vin[0] / Vec_Len(vin);
vout[1] = vin[1] / Vec_Len(vin);
vout[2] = vin[2] / Vec_Len(vin);

} aliasing

suppose A call Vec_Unit:

Vec_Unit(v1, v1), intended;

to normalize v1

the fix: use temp var.

for Vec_Len(v1)

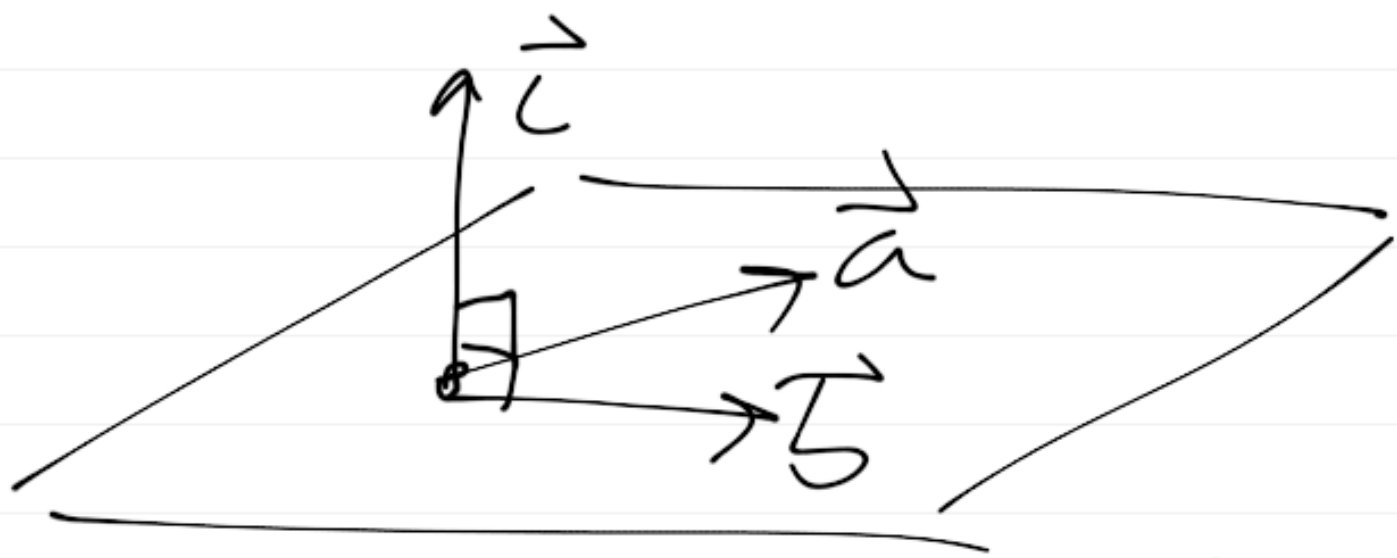
len = Vec_Len(v1)

v2[0] = v1[0] / len

⋮

Cross product

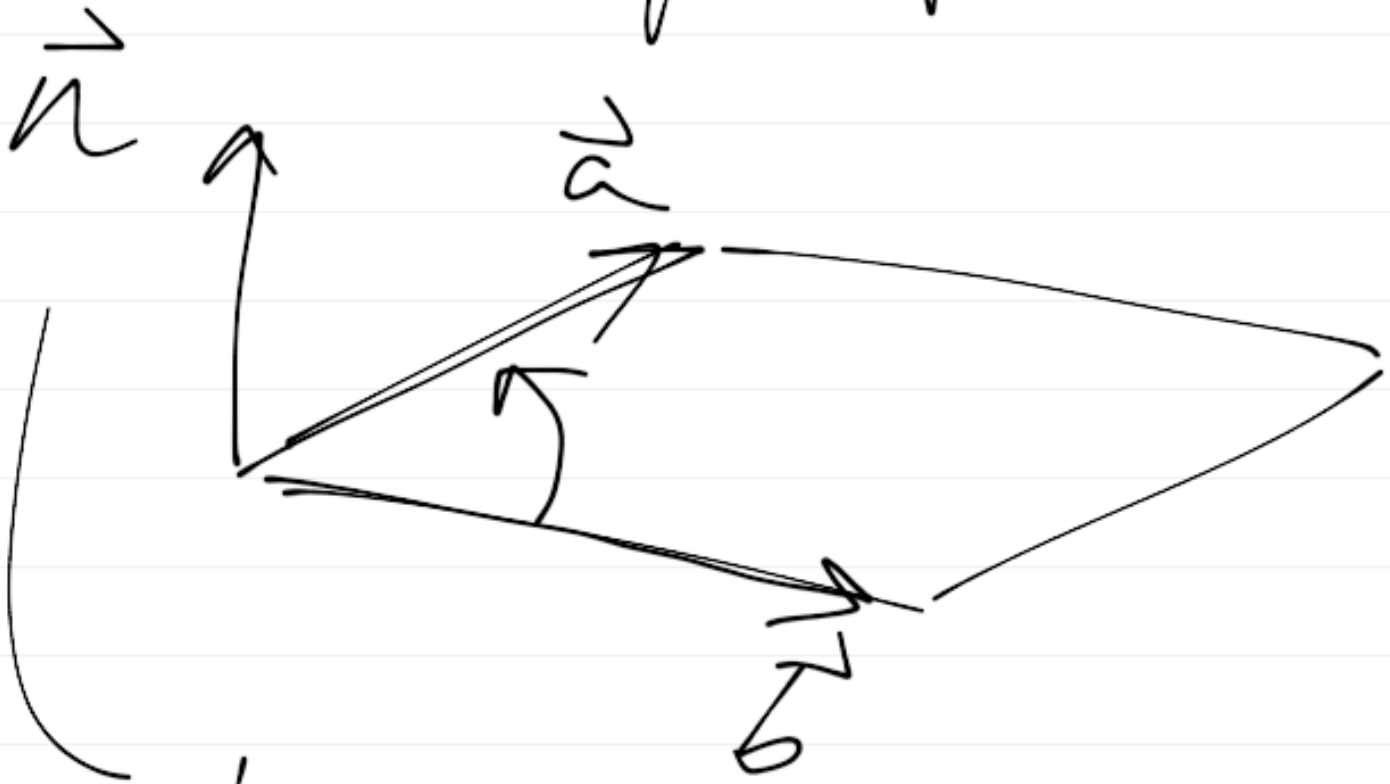
$$\vec{c} = \vec{b} \times \vec{a}$$



\vec{c} is perpendicular (\perp)
to both \vec{a} and \vec{b} ("orthogonal")

(above, $\vec{b} \times \vec{a}$ uses right-hand rule)

We need this to determine
orientation of a plane



plane
normal: Vec. in dir
of plane

$$\begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix} \times \begin{pmatrix} b_x \\ b_y \\ b_z \end{pmatrix} = c_x$$

$$a_y b_z - a_z b_y$$

$$a[1] * b[2] - a[2] * b[1]$$

$$\begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix} \times \begin{pmatrix} b_x \\ b_y \\ b_z \end{pmatrix} = c_y$$

$$a_z b_x - a_x b_z$$

$$a[2] * b[0] - a[0] * b[2]$$

$$\begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix} \times \begin{pmatrix} b_x \\ b_y \\ b_z \end{pmatrix} = c_z$$

$$a_x b_y - a_y b_x$$

$$a[0]b[1] - a[1]b[0]$$

$$\text{Vec_cross}(v_1, v_2, v_3)$$

$$v_1 \times v_2 = \text{result}$$

$$v_3[0] = v_1[1]v_2[2] - v_1[2]v_2[1]$$

$$v_3[1] = v_1[2]v_2[0] - v_1[0]v_2[2]$$

$$v_3[2] = v_1[0]v_2[1] - v_1[1]v_2[0]$$

int i

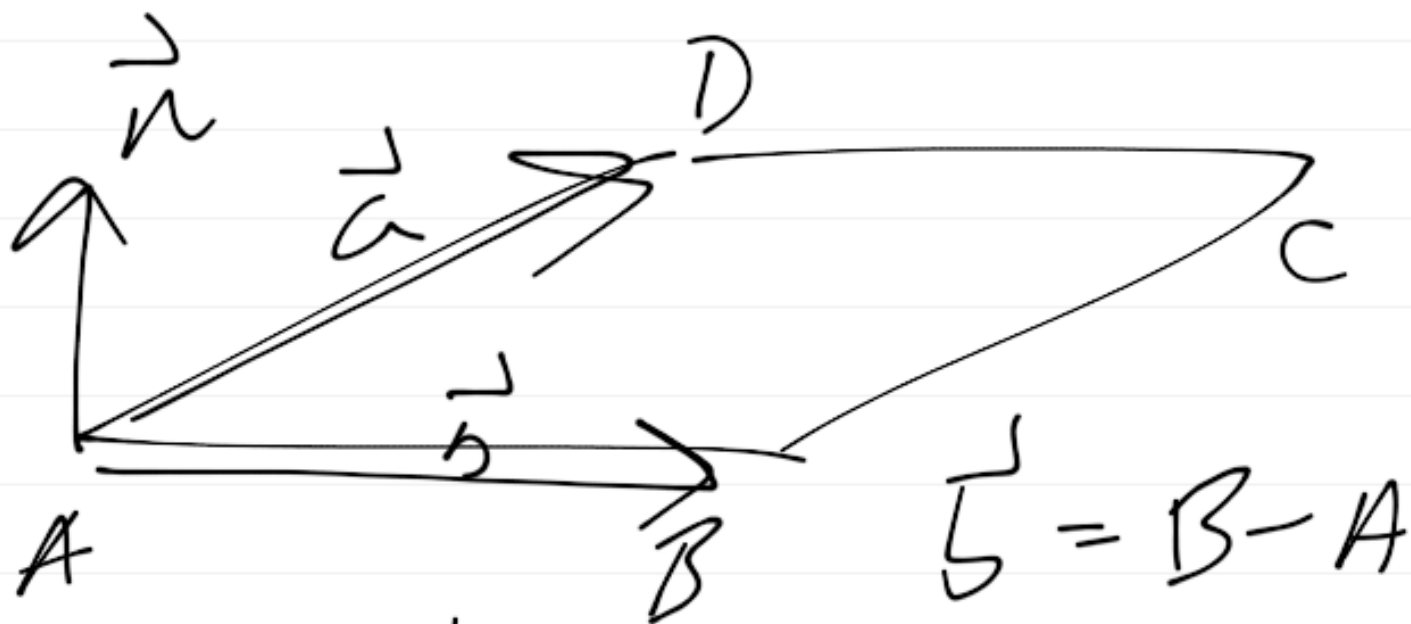
vector w;

for (i = 0; i < 3; i++)

w[i] =

$$v_1[(3+i+1) \% 3]v_2[(3+i-1) \% 3] -$$

$$v_1[(3+i-1) \% 3]v_2[(3+i+1) \% 3]$$



$$\vec{n} = \vec{b} \times \vec{a}$$

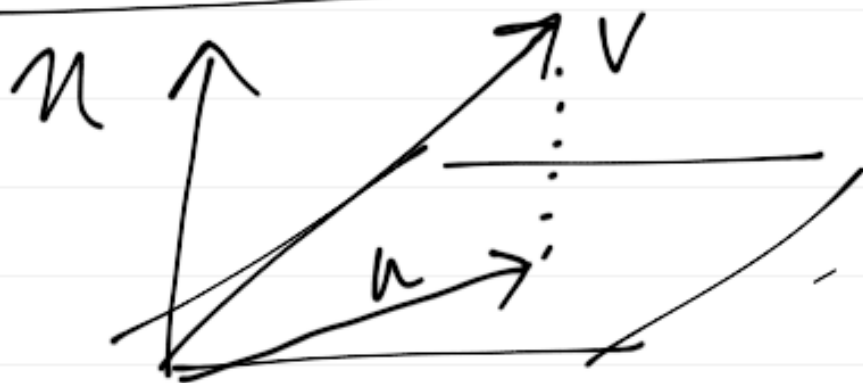
$$= \frac{(B - A)}{\|B - A\|} \times \frac{(D - A)}{\|D - A\|}$$

Vec-project (n, v, u)

Result:

the projection u
of vector v onto plane
defined by n (normal)

$$u = v - (v \cdot n)n$$



$\text{vec}_t w; // \text{work vec}$

$\text{vec_scale}(-\text{vec_dot}(v, w),$
 $u,$
 $w)$

$\text{vec_sum}(v, w, u)$

$\text{vec_unit}(u, u) // \text{to}$

normalize u

in C++ : use operators

Code looks almost

like math eg.

in Obj, C :

[u sum: v : w];

something similar ...

- Building a linked list
- Want a generic list
(in C++ parlance, a container)
- We'll use it for our scene objects
- the list is composed of
2 data types:
list (header) , link (node)

```
typedef struct _link
```

```
{  
    struct _link *next;
```

```
    void *data;
```

```
} link_t;
```

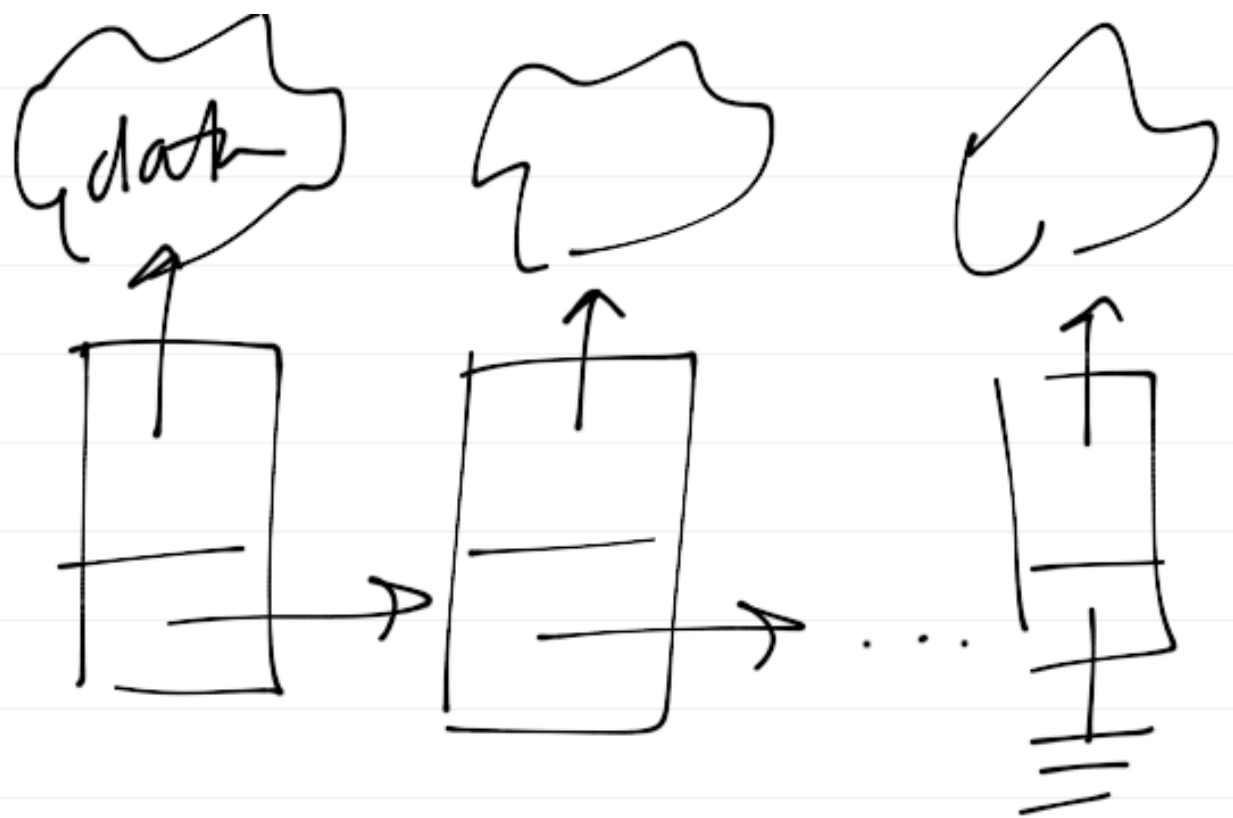
void * data;

void or *data;

?

void * data1, data2:

void *data1, void data2;



- for every data type
(like `link_t`)

write "object constructor"
(memory alloc & init)

- usage:

link_t *link =

link_init (data);

↑
ptr to data


```
#include <assert.h>
```

```
#include "list.h"
```

```
link_t link_init(void *data)
```

```
{
```

```
link_t *link =
```

```
(link_t *) malloc(  
    sizeof(link_t));
```

```
assert(link != NULL);
```

— OR —

link_t *link = NULL;

if (! (link = (link_t *)
malloc(sizeof(link_t)))
~~== NULL~~)

{
printf(stderr, "out
of memory\n");
exit(1);

}

— or — // assert

link → next = NULL;

link → data = data;

return (link);

} // link constructor

list header



one of these per list

typedef struct _list

{

link_t *first, *last;

link_t *current;

} list_t

Usage:

```
list_t *elist = NULL;
```

```
elist = list_init();
```

```
list_t * list_init(void)
```

```
list_t *hdr = NULL;
```

```
hdr = (list_t *) malloc(  
    sizeof(list_t));
```

```
assert(hdr != NULL);
```

hdr → first =

hdr → last =

hdr → current = NULL;

return (hdr);

}



```
int list_empty (list_t  
                * list)
```

```
if (list->first == NULL)  
    return 1;
```

_____ or _____

```
return (list->first == NULL ?  
        1 : 0);
```

```
}
```