

from last time:

object_t *
obj →

plane_t *
plane →

int	cookie
char	type [...]
char	name [...]
material_t *	mat
void (*printer)	(...)
void (*hits)	(...)
void (*ambient)	(...)
:	
Vec_t	last_normal
Vec_t	normal
Vec_t	point
double	ndotg

hits function:

- like object_print()

≠ plane_print()

⇒ virtual function

⇒ plane_print()

overrides object_print()

[plane_print calls object_print

but plane → hits()

does not call obj → hit()]

Recall:

```
plane_print(object_t *obj,  
            FILE *out)
```

```
{
```

```
    // print first (common)
```

```
    // part of plane object
```

```
    // plane wall
```

```
    { material tag
```

```
    object_print(obj);
```

```
    // now gain access to
```

```
    // rest of extra struct
```

```
    plane_t *pla =
```

```
type cast → (plane_t *)obj;
```

```
// and print out rest of plane
```

```
//     normal  0  1  0
```

```
//     point   3  0  0
```

```
// }  
}
```

```
vec_print(out, "  
plane → normal);
```

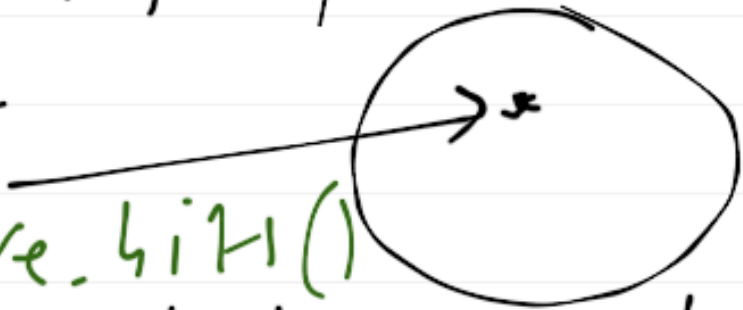
```
vec_print(out, "  
plane → point);
```

```
fprintf(out, " } \n \n");
```

```
}
```

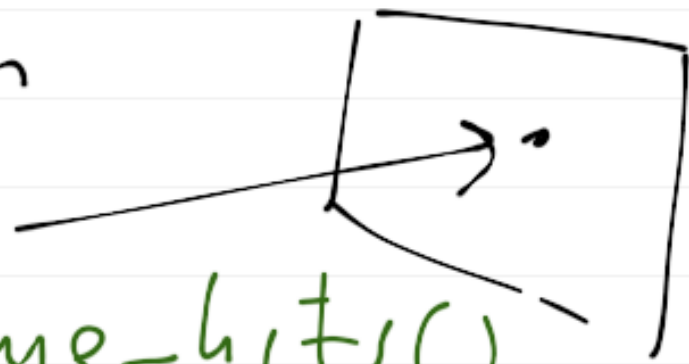
hits() works the same way:

- sphere will have a hits() function



sphere_hits()

- plane will have a hits() function



plane_hits()

- using plane_init():

obj → hits = plane_hits;

- using sphere_init():

obj → hits = sphere_hits;

revisit:

```
plane_init (FILE *in,  
            list_t *objs,  
            list_t *mats,  
            int attrmax)
```

}

// allocate memory:

```
plane_t *ply =
```

```
(plane_t *) malloc (sizeof(  
    plane_t));
```

```
if (ply == NULL) // error
```

```
// zero out
```

```
memset (ply, 0, sizeof (plane_t))
```

// init parent structure

object_t *obj =

(object_t *)ply;

type cast, no malloc

object_init(obj, in, obj, mats);

// set type string

strcpy(obj->type, "plane");

// overload virtual functions

obj->printer = plane_print;

obj->hits = plane_hits;

// continue parsing file

```
while ((c = fgetc(in)) != EOF  
      && c != '{') {
```

```
    fputc(c, in);
```

```
    fscanf(in, "%s", attrname)
```

```
    if (!strcmp(attrname, "normal"))
```

```
        vec_read(in, ptr → normal)
```

```
    if (!strcmp(attrname, "point"))
```

```
        vec_read(in, ptr → point)
```

```
    while ((c = fgetc(in)) != EOF
```

```
          && c != '\\n');
```


// finished parsing set parent
// values

Vec_unit (plu → normal,
obj → last_normal);

// normalize plu → normal

Vec_unit (plu → normal,
plu → normal);

// set ϵ dot z

plu → ϵ dot z = Vec_dot (
plu → point, plu → normal);

}

Remember:

object init (obj_t * obj,
FILE * in,
list_t * objl,
list_t * mats)

```
{ obj->cookie = OBJ_COOKIE;
```

```
  fscanf(in, "%s", obj->name);
```

```
  // parse first part of object
```

```
  while ((c = fgetc(in)) != EOF
```

```
    && c != '{');
```

```
  fscanf(in, "%s", attrname);
```

```
fscanf(in, "%s", matname);
```

↑
material name
4.5, b1k

```
obj->mat =
```

```
material_get_by_name(  
    mats, matname);
```

```
// consume whitespace til EOL
```

```
while ((c = fgetc(in)) != EOF  
    && c != '\n');
```

|| init default - virtual

|| functions

obj → pointer = object - point;

obj → hits = object - 40 - hit;

obj → ambient =

material - get amb;

obj → diffuse =

material - get diff;

obj → specular =

material - get spec;

} list_add (objs, (void *) obj);

double

object_has_hit (object_t *obj,

vec_t base,

vec_t dir)

{

printf(stderr,

"object %s failed to

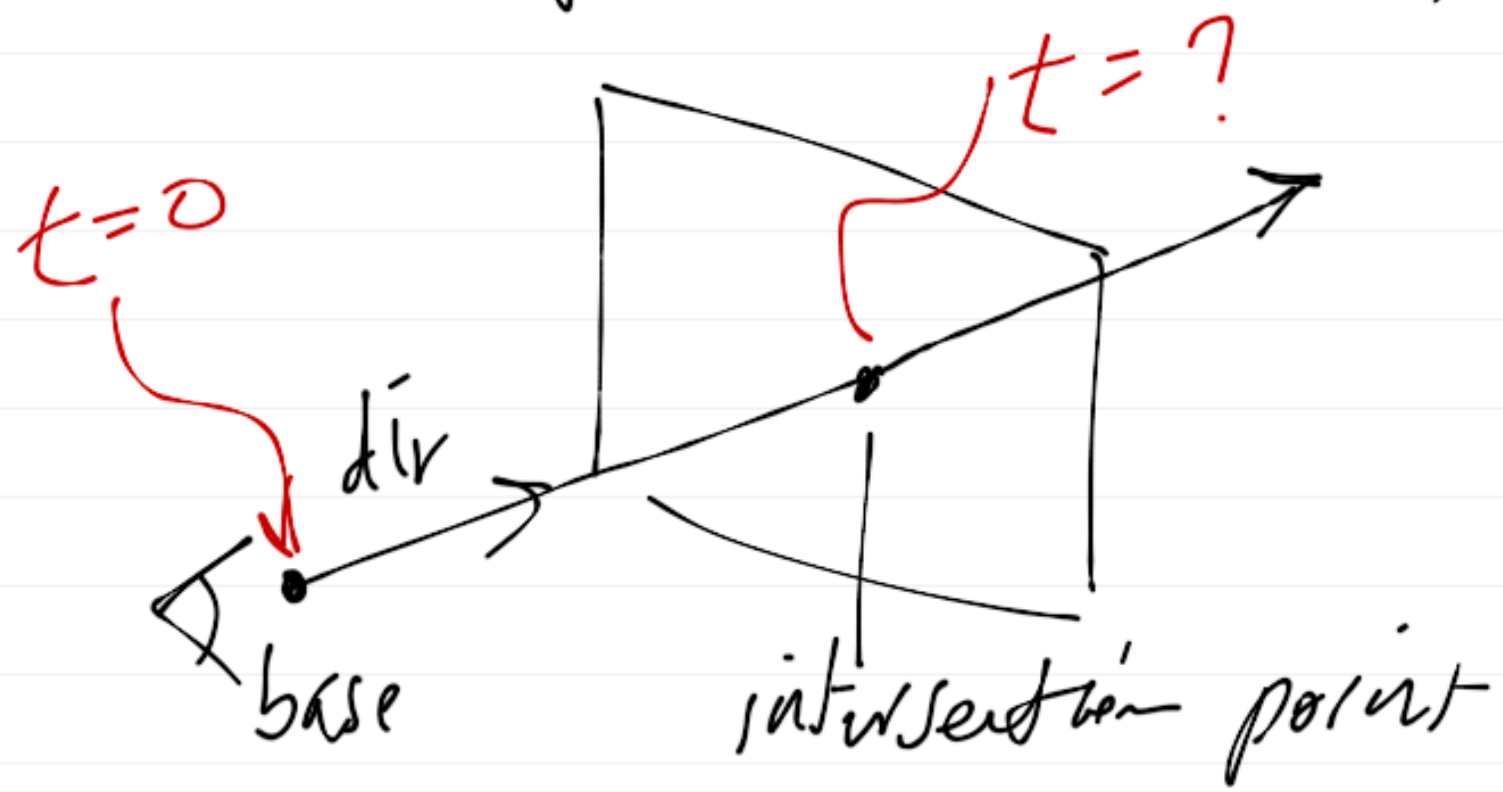
provide hit function",

obj->name);

return (-1.0);

}

- What is plane-hits supposed to do?
- return double t value along ray at ray-plane intersection point
(see p. 72 in PDF notes)



- remember

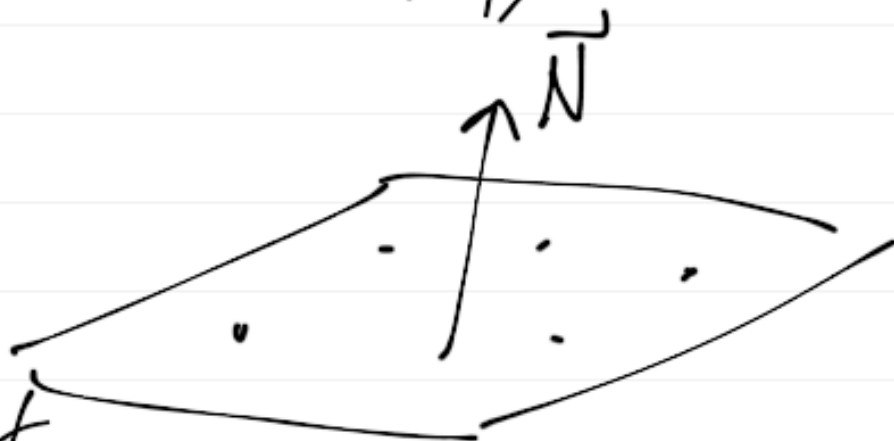
$\text{pln} \rightarrow \text{normal} = \text{Vec_dot}(\text{pln} \rightarrow \text{normal}, \text{pln} \rightarrow \text{point})$

- plane is defined by plane

equation:

$$Ax + By + Cz + D = 0$$

for any point (x, y, z) on
the plane



A, B, C, D just

scales but $\vec{N} = (A, B, C)$

- given $pln \rightarrow normal = (A, B, C)$
(from file)

Solve for D

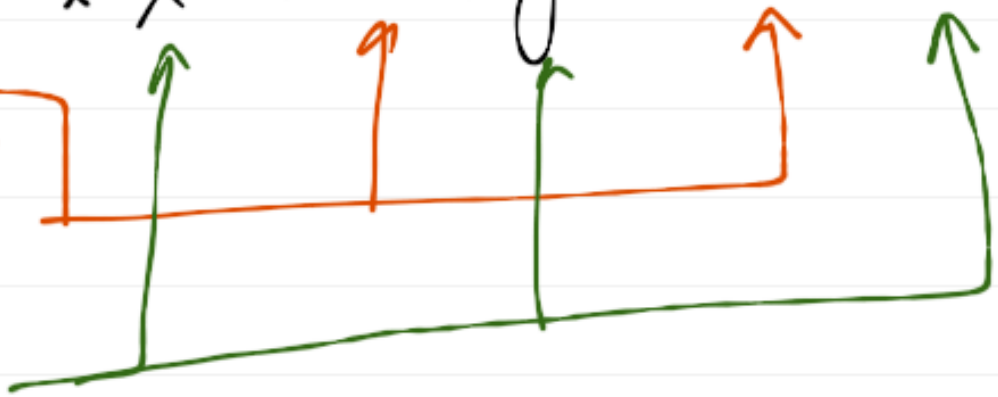
- need known point on the
plane, $pln \rightarrow point = (x, y, z)$

also from file

$$A * x + B * y + C * z$$

$pln \rightarrow normal$

$pln \rightarrow point$



rewrite in vector notation

$$\begin{pmatrix} A \\ B \\ C \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad \text{dot product.}$$

$$Ax + By + Cz + D = 0$$

solve for D :

$$D = -(Ax + By + Cz)$$

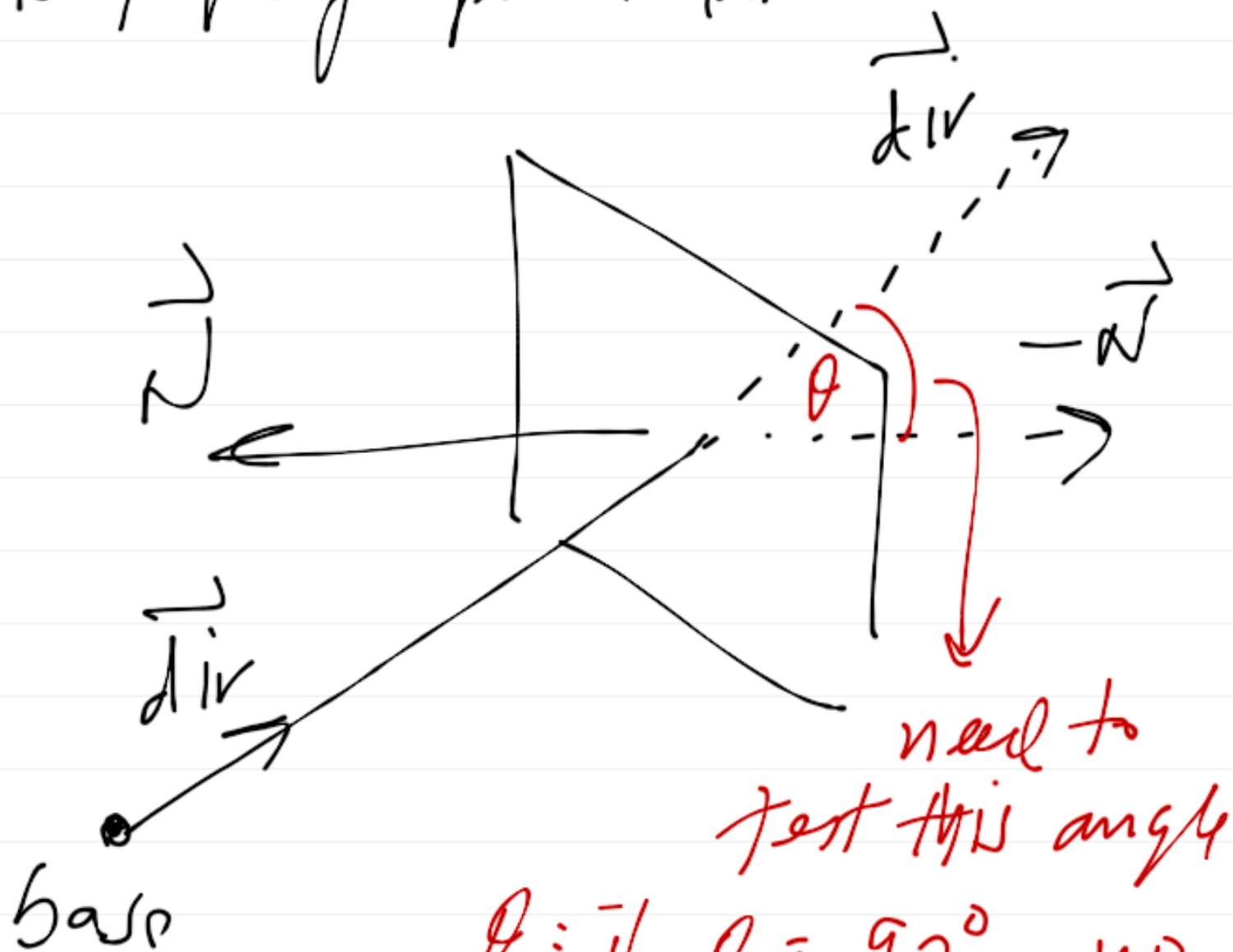
$$= - \left[\begin{pmatrix} A \\ B \\ C \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} \right]$$

$$= - \vec{N} \cdot \vec{p}$$

$\vec{p} \rightarrow$ point $\vec{N} \rightarrow$ normal
 $\vec{p} \rightarrow$ point $\vec{N} \rightarrow$ normal
 $\vec{p} \rightarrow$ point $\vec{N} \rightarrow$ normal

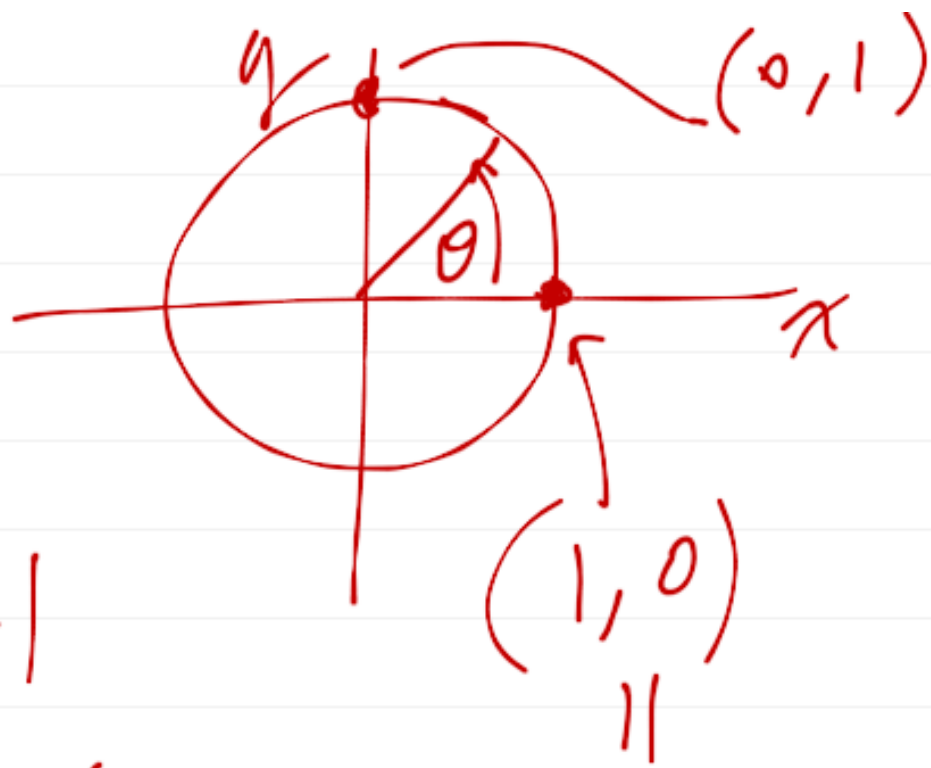
$\vec{p} \rightarrow$ point $\vec{N} \rightarrow$ normal
 $\vec{p} \rightarrow$ point $\vec{N} \rightarrow$ normal
 $\vec{p} \rightarrow$ point $\vec{N} \rightarrow$ normal

Now, ray-plane intersection:



θ : if $\theta = 90^\circ$, no intersection

$$\cos \theta = \frac{-\vec{N} \cdot \vec{dir}}{\|\vec{N}\| \|\vec{dir}\|}$$



$$\cos(0) = 1$$

$$\cos(90) = 0$$

$$\left(\cos \theta, \sin \theta \right)$$

$$\Rightarrow \vec{n} \cdot \vec{dir} = 0.0$$

$\Rightarrow \theta = 90^\circ$, no intersection

return -1

- plane_bits alg:

① $n \cdot dir = n \cdot dir$
(use `vec_dot`)

if ($n \cdot dir == 0.0$)
return (-1.0)

Testing
floating pt.
equality, watch it!
use `fabs()`

② ($N \cdot dir$ is not 0 so we have intersection)

calculate distance from ray's base to plane:

- calculate $\vec{N} \cdot \vec{base}$,

$$n \cdot b = \vec{N} \cdot \vec{base};$$

- subtract from D and scale by $1/(\vec{N} \cdot \vec{dir})$

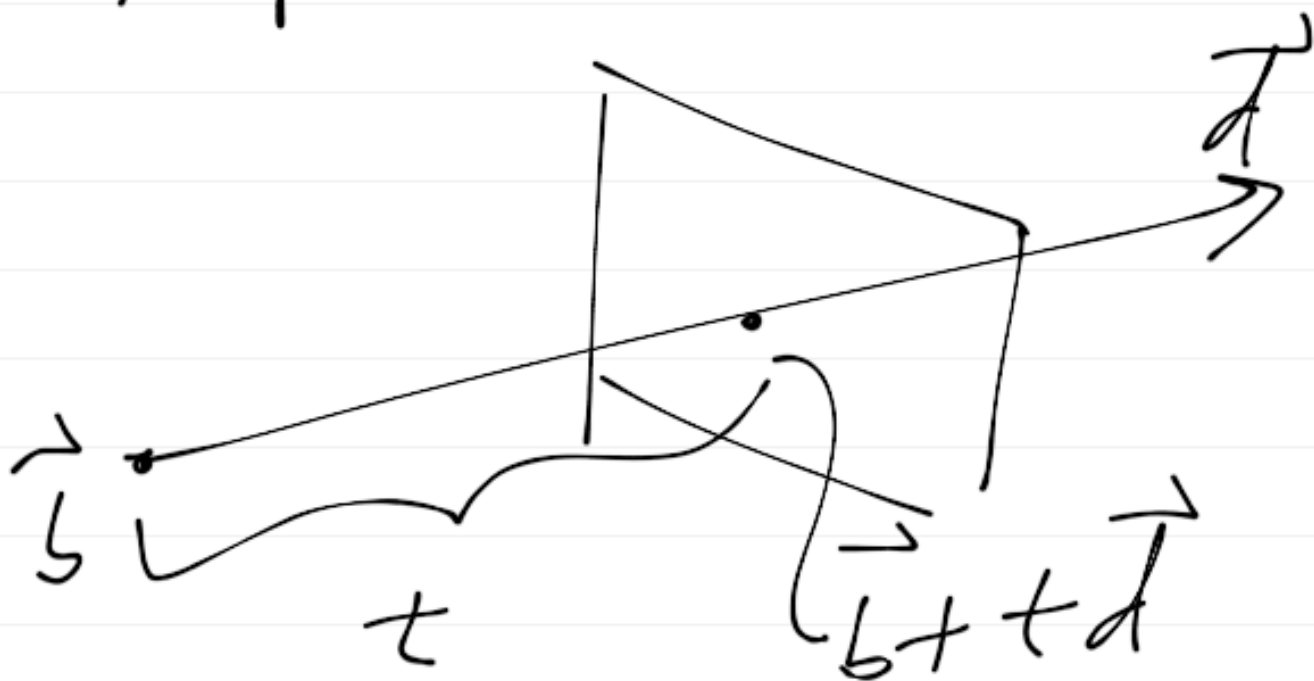
$$t = (D - (\vec{N} \cdot \vec{base})) / (\vec{N} \cdot \vec{dir})$$

$$t = (pln \cdot n \cdot dot \cdot s - n \cdot dot \cdot b) / n \cdot dot \cdot d;$$

③ if $t \leq 0$, intersection
is behind base point
if $(t \leq 0)$ return (-1)

④ calculate hit point

$$\text{hit point} = \text{base} + t * \vec{dir}$$



Vec_scale(t , \vec{dir} , obj, \rightarrow last_hit)

Vec_sum(obj, \rightarrow last_hit,
base,
obj, \rightarrow last_hit)

// if $z > 0$, hit point

// in front of image plane

// invalid

if (obj, \rightarrow last_hit[2] > 0.0)

return (-1.0);

return (t);

}

Numerical example:

$$\text{plane: } \vec{N} = 0 \ 0 \ 1$$

$$p = 0 \ 0 \ -7$$

$$\text{ray: } \text{pos} = 4 \ 3 \ 5$$

$$\text{dir} = 0 \ 0 \ -1$$

① normalize plane dir

$$\text{Vec_Unit}(\text{dir}, \text{dir})$$

$$\sqrt{0^2 + 0^2 + 1^2} = \sqrt{1^2} = 1$$

$$\text{dir} = \frac{1}{1} \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix}$$

$$\textcircled{2} \text{ u dot d} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} = \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix} = -1$$

$$\textcircled{3} \text{ u dot b} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 4 \\ 3 \\ 5 \end{pmatrix} = \begin{bmatrix} 0 \\ 0 \\ 5 \end{bmatrix} = 5$$

$$\textcircled{4} \frac{\text{u dot g} - \text{u dot b}}{\text{u dot d}} = \frac{-7 - 5}{-1} = 12$$

$$\text{(because u dot g} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{pmatrix} 4 \\ 0 \\ -7 \end{pmatrix} = -7$$

$\textcircled{5}$ mit pivot: base + t \vec{u}

$$\begin{pmatrix} 4 \\ 3 \\ 5 \end{pmatrix} + 12 \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 4 \\ 3 \\ 5-12 \end{pmatrix} = \begin{pmatrix} 4 \\ 3 \\ -7 \end{pmatrix}$$