Research Log

Stage 1: Environment preparation:

• Install/check anaconda

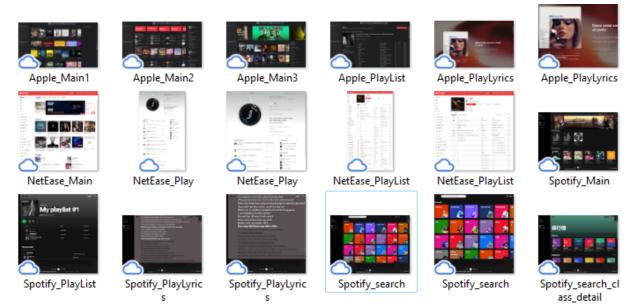
conda -V

```
[>________j@node0209 ~]$ conda -V
conda 4.12.0
```

- Create new virtual environment: conda create -n yolov5 python=3.9
- Activate the conda virtual environment:(palmetto) source activate yolov5 # for linux
- Download the Yolo-v5 code: git clone https://github.com/ultralytics/yolov5 # clone
- Goto the yolov5 folder: cd [path_to_yolov5]
- Install the required packages: pip install -r requirement.txt

Stage 2: Labels and picture preparation:

• Prepare the pictures:



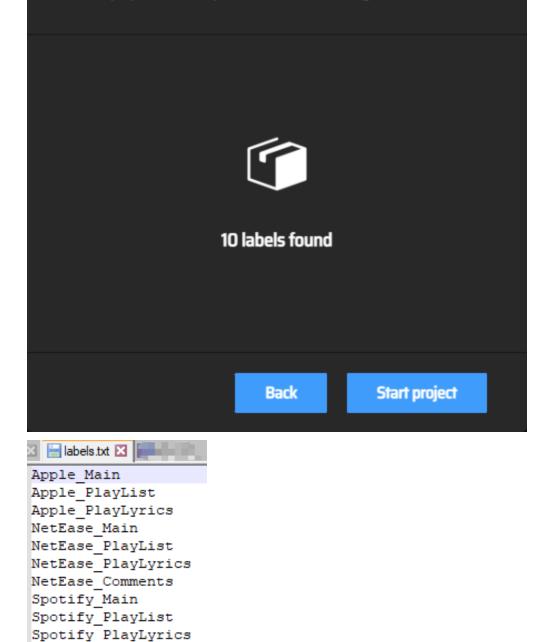
• Label the picture on image labeling tools: WebSite



• Load the pictures and load the labels from file:

Load file with labels description

Load a text file with a list of labels you are planning to use. The names of each label should be separated by new line. If you don't have a prepared file, no problem. You can create your own list now.

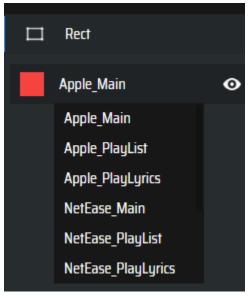


• Start Labeling picture:

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• Select label:



• Export labels:

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	➡ Edit Labels 🔍
31	🖸 Import Images
	Import Annotations
	Export Annotations
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	🗴 Connect Al server
	Export rect annotations
□	Select label type and the file format you would like to use to export labels.
\mathbf{i}	
\bigcirc	A .zip package containing files in YOLO format.
	A .zip package containing files in VOC XML format.
	Single CSV file.
-	
	Cancel Export

• Put the image file and the label files(txt and XML) under the yolov5 folder:

🖿 / 🚥 / paper_data / images /

Name		Last Mc
🔀 Apple_Main1.jpg		25 da
🔣 Apple_Main2.jpg		25 da
🔣 Apple_Main3.jpg		25 da
🖪 Apple_PlayList.jpg		25 da
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NetEase_PlayLyric2.png		20 daj
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Name		Last Modified
Apple_Main1.xml		20 days ago
Apple_Main2.xml		20 days ago
Apple_Main3.xml		20 days ago
Apple_PlayList.xml		20 days ago
Apple_PlayLyrics.xml		20 days ago
NetEase_Main.xml		20 days ago
NetEase_Play.xml		20 days ago
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1	<pre><annotation></annotation></pre>
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2	<pre>——w<folder>my-project-name</folder> </pre>
3	<pre>——w<filename>Apple_Main2.jpg</filename></pre>
4	<pre>—_w<path>/my-project-name/Apple_Main2.jpg</path></pre>
5	
6	<pre></pre>
7	
8	* <size></size>
9	
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13	* <object></object>
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Apple_Main1.txt	20 days ago
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Apple_PlayList.txt	20 days ago
Apple_PlayLyrics.txt	20 days ago
🗅 NetEase_Main.txt	20 days ago
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E NetEase_PlayLyric3.txt \times

1 3 0.41588541666666667 0.2633620689655172 0.3348958333333334 0.4508620689655172 2 3 0.411458333333333 0.7021551724137931 0.344791666666666666 0.40086206896551724 3

Stage 3: Dataset preparation:

E sp	plit_train_val.py	\times	≣ train.txt	×	≣ val.txt	×	
1	<pre># coding:utf-8</pre>						
2	import os						
З	import random						
4	import argparse						
5							
6	1 01						
						generally stored unde	
							_data/Annotations', type=str, help='input xml label path')
						type=str, help='input	t xml label path')
	#Division of datase						
							utput txt label path')
				'/home		/yolov5/paper_	_data/ImageSets/Main', type=str, help='output txt label path
	opt = parser.parse	args	0				
4	1						
	trainval_percent =						
	<pre>train_percent = 0.9 xmlfilepath = opt.></pre>		-+h				
	txtsavepath = opt.1						
	total xml = os.list						
	if not os.path.exis		1				
1	os.makedirs(txt						
2							
	num = len(total xm])					
	print('total xml',						
	list index = range						
6	tv = int(num * trai	nval	percent)				
	tr = int(tv * train						
8	trainval = random.	ample	e(list_index, tv)				
9	train = random.samp	le(t	rainval, tr)				
0							
1	<pre>file_trainval = ope</pre>	en(txt	tsavepath + '/train	val.txt', 'v	«')		
	file_test = open(t)						
	file_train = open(1						
	<pre>file_val = open(txt</pre>	save	<pre>path + '/val.txt',</pre>	'w')			
5							
	for i in list_index						
7	name = total_xr		[:-4] + '\n'				
8	if i in trainva						
9	file_train		rite(name)				
0 1	if i in tra		write(name)				
2	else:	ain.	write(name)				
2		1	ite(name)				
1	else:	α τ ι W1"3	rec(name)				
+ 5	file_test.	rite	(name)				
6	TIE_CESC.	. ICC	(name)				
	file trainval.close	0					
	file_train.close()	~~~					

- Run the code: python3 split_train_val.pyResult: train set and validation set.

≣ train.txt	× ≣ val.txt	×
<pre>/yolov5/paper_dat /yolov5/paper_dat /yolov5/paper_dat /yolov5/paper_dat /yolov5/paper_dat /yolov5/paper_dat /yolov5/paper_dat /yolov5/paper_dat /yolov5/paper_dat /yolov5/paper_dat</pre>	ta/images/NetEase_PlayLis ta/images/NetEase_PlayLys ta/images/Spotify_search_ ta/images/Apple_PlayLyris ta/images/Apple_PlayLyris ta/images/Spotify_PlayLyris ta/images/NetEase_Play.j ta/images/NetEase_Play.j ta/images/NetEase_Play.j ta/images/NetEase_PlayLyris ta/images/Spotify_PlayLyris ta/images/Spotify_PlayLyris	st.jpg ric1.jpg _class_detail.jpg g cs.jpg rics.jpg g pg pg pg ric2.jpg ric2.jpg st.jpg

- Create the label files:
- python3 voc_label.py



Apple_Main1.txt	NetEase_Play.txt 🛛
Apple_Main2.txt	1 5 0.515432 0.173168 0.944444 0.294326 2 6 0.506173 0.645390 0.950617 0.626478
Apple_Main3.txt	
🔀 Apple_PlayList.txt	
🔀 Apple_PlayLyrics.txt	
🔀 NetEase_Main.txt	
📑 NetEase_Play.txt	
📑 NetEase_PlayList.txt	
📑 Spotify_Main.txt	
📑 Spotify_PlayList.txt	
Spotify_PlayLyrics.txt	
🔀 Spotify_search.txt	
📑 Spotify_search_class_detail.txt	

• Setup the yaml settings: the path and the labels

```
1 path: /home/ _____ _ _____ /yolov5/paper_data/ # dataset root dir
3 val: /home/_____T/yolov5/paper_data/images
4 test: # test images (optional)
5
6 # number of class
7 nc: 10
8
9
10 classes: ['Main','PlayList','PlayLyrics','Comments']
11 # # class names
12
13 CLASS NAMES: ['Main', 'PlayList', 'PlayLyrics', 'Comments'] # my own labels
14 # Classes
15 names:
16 0: Main
17
   1: PlayList
18 2: PlayLyrics
   3: Comments
19
```

Stage 4: Options preparation:

• Setting the training parameters: Weights(which model), settings(yaml), epochs, batch size etc.

```
def parse opt(known=False):
    parser = argparse.ArgumentParser()
    parser.add_argument('--weights', type=str, default=ROOT / 'yolov5m.pt', help='initial weights path')
    parser.add_argument('--cfg', type=str, default='models/yolov5m.yaml', help='model.yaml path')
    parser.add_argument('--data', type=str, default=ROOT / 'data/eyeTrack.yaml', help='dataset.yaml path')
parser.add_argument('--hyp', type=str, default=ROOT / 'data/hyps/hyp.scratch-low.yaml', help='hyperparameters path')
    parser.add_argument('--epochs', type=int, default=10, help='total training epochs')
    parser.add_argument('--batch-size', type=int, default=16, help='total batch size for all GPUs, -1 for autobatch')
    parser.add_argument('--imgsz', '--img', '--img-size', type=int, default=640, help='train, val image size (pixels)')
    parser.add_argument('--rect', action='store_true', help='rectangular training')
    parser.add_argument('--resume', nargs='?', const=True, default=False, help='resume most recent training')
    parser.add_argument('--nosave', action='store_true', help='only save final checkpoint')
    parser.add_argument('--noval', action='store_true', help='only validate final epoch')
    parser.add_argument('--noautoanchor', action='store_true', help='disable AutoAnchor')
    parser.add_argument('--noplots', action='store_true', help='save no plot files')
    parser.add_argument('--evolve', type=int, nargs='?', const=300, help='evolve hyperparameters for x generations')
parser.add_argument('--bucket', type=str, default='', help='gsutil bucket')
    parser.add_argument('--cache', type=str, nargs='?', const='ram', help='image --cache ram/disk')
    parser.add_argument('--image-weights', action='store_true', help='use weighted image selection for training')
    parser.add_argument('--device', default='0', help='cuda device, i.e. 0 or 0,1,2,3 or cpu')
    parser.add_argument('--multi-scale', action='store_true', help='vary img-size +/- 50%%')
    parser.add_argument('--single-cls', action='store_true', help='train multi-class data as single-class')
    parser.add_argument('--optimizer', type=str, choices=['SGD', 'Adam', 'AdamW'], default='SGD', help='optimizer')
    parser.add_argument('--sync-bn', action='store_true', help='use SyncBatchNorm, only available in DDP mode')
    parser.add_argument('--workers', type=int, default=8, help='max dataloader workers (per RANK in DDP mode)')
parser.add_argument('--project', default=ROOT / 'runs/train', help='save to project/name')
    parser.add_argument('--name', default='exp', help='save to project/name')
    parser.add_argument('--exist-ok', action='store_true', help='existing project/name ok, do not increment')
    parser.add_argument('--quad', action='store_true', help='quad dataloader')
    parser.add_argument('--cos-lr', action='store_true', help='cosine LR scheduler')
    parser.add_argument('--label-smoothing', type=float, default=0.0, help='Label smoothing epsilon')
    parser.add_argument('--patience', type=int, default=100, help='EarlyStopping patience (epochs without improvement)')
    parser.add_argument('--freeze', nargs='+', type=int, default=[0], help='Freeze layers: backbone=10, first3=0 1 2')
    parser.add_argument('--save-period', type=int, default=-1, help='Save checkpoint every x epochs (disabled if < 1)')
    parser.add_argument('--seed', type=int, default=0, help='Global training seed')
    parser.add_argument('--local_rank', type=int, default=-1, help='Automatic DDP Multi-GPU argument, do not modify')
    # Logger arguments
    parser.add_argument('--entity', default=None, help='Entity')
```

parser.add_argument('--upload_dataset', narg5='?', const=True, default=False, help='Upload data, "val" option')
parser.add_argument('--bbox_interval', type=int, default=-1, help='Set bounding-box image logging interval')
parser.add_argument('--artifact_alias', type=str, default='latest', help='Version of dataset artifact to use')

return parser.parse_known_args()[0] if known else parser.parse_args()

• Training the model:

python train.py --img 640 --batch 8 --epoch 501 --data data/eyeTrack.yaml --cfg models/yolov5m.yaml --weights weights/yolov5m.pt --device '0'

-ing 640 --devic cyuyam --data data/myvoc.yaml --epoch 200 --batch-size 8 --train: weights-weights/yolov5s.cg. cfgemodels/yolov5s.yaml, data-data/myvoc.yaml, hyp-data/hyps/hyp.scratch-low.yaml, epochs=200, batch_size=8, imgsz=640, rect=False, resume=False, nosave=False, noval=False, nosautcanchor=False, noplots=False, evolve=Hone, bucket=, cache=Hone, image_weights=False, device=cpu, multi_scale=False, single_cls=False, optimizer=S60, sync_bn=False, workers=8, project=runs/train, name=e xp, exist_ocl=False, quad=False, cos_ir=False, label_smoothing=0.0, patience=100, save_period=-1, seed=0, local_rank=-1, entity=Hone, upload_dataset=False, bbov_interval=-1, artifact_allas=latest github: up to date with https://github.com/ultralytics/yolov5 @ Traceback (most recent call last): File "/home/xiangy//pythonProject/8810ET/yolov5/train.py", line 640, in <module> main(opt)

le "/home, nain(opt)

main(opt)
file "/home/iangyi/pythonProject/8510ET/yolov5/train.py", line 504, in main
 check file(opt.data), check yaml(opt.cfg), check yaml(opt.hyp), str(opt.weights), str(opt.project) # checks
 file "/home/iangyi/pythonProject/8510ET/yolov/strlis/general.py", line 401, in check_file
 assert len(files), f'file not found: (file)' # assert file was found
 AssertionError: File not found: (dia/myvoc.yaml
 --img 640 --device cpuml --data data/veyroc.yaml
 --img 640 --device cpuml

t github: up to date with https://github.com/ultralytics/yolov5 ☑ YOLOv5 ŵv7.0-117-g85f6019 Python-3.9.16 torch-1.13.1+cu117 CPU

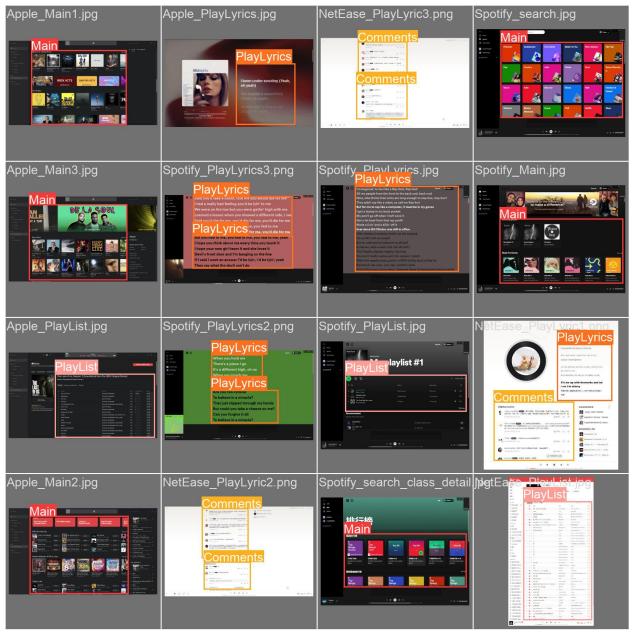
hyperparameters: 1r0+0.01, lrf=0.01, momentum=0.937, weight_decay=0.0005, warmup_epochs=3.0, warmup_momentum=0.8, warmup_bias_lr=0.1, box=0.05, cls=0.5, cls_pu=1.0, obj=1.0, obj=1.0, obj=1.0, obj=0.2, anchor_t=4 .0, flggmma=0.0, hov_h=0.015, hsv_s=0.7, hsv_v=0.4, degrees=0.0, translate=0.1, scale=0.5, bespective=0.0, flipud=0.0, flipud=0.0, flipud=0.0, copy_past==0.0 ClearML: run 'pip install clearML' to automatically track and visualize YOLOVS from Sin ClearML Comet: run 'pip install comet_ml' to automatically track and visualize YOLOVS from Sin ClearML Comet: run 'pip install comet_ml' to automatically track and visualize YOLOVS from Sin ClearML Comet: run 'pip install comet_ml' to automatically track and visualize YOLOVS from Sin ClearML Comet: run 'pip install comet_ml' to automatically track and visualize YOLOVS from Sin ClearML Comet: run 'pip install comet_ml' to automatically track and visualize YOLOVS from Sin ClearML Comet: run 'pip install comet_ml' visual thrutp://localhose/060/ 2023-09.10:40:070.0654500: I tensorFlow/core/platform/cpu_feature_guard.cc:193] This TensorFlow binary is optimized with oneAPI Deep Neural Network Library (oneDNN) to use the following CPU instructions in performance-critical operations: AVXZ FVA To enable them in other coverations. rehuild TensorFlow with the anoncoviate compiler flags.

	Class all	Images 13	Instances 14	P 0.747	R 0.667	mAP50 0.829	0.691
Epoch 299/299	GPU_mem 3.3G Class	box_loss 0.01993 Images	0.01809	cls_loss 0.03063 P	Instances 18 R	Size 640: 1 mAP50	
	all	13	14	0.747	0.667	0.829	0.691
300 epochs com Optimizer stri Optimizer stri	pped from pped from	runs/train runs/train	/exp12/weig /exp12/weig	hts/best.pt	-		
Validating run Fusing layers.		cp12/weight	s/best.pt				
YOLOV5m summar		vers, 20889	303 paramete	ers. 0 grad	ients. 48.0	GELOPS	
	Class	Images	Instances	, - 8 P	R	mAP50	
	all	13	14	0.76	0.667	0.884	0.741
Ap	ple_Main	13	3	0.618	1	0.995	0.785
Apple_	PlayList	13	1	0.732	1	0.995	0.895
Apple_Pl	ayLyrics	13	1	0.716	1	0.995	0.697
NetE	ase_Main	13	1	0.823	1	0.995	0.995
NetEase_	PlayList	13	1	1	0	0.995	0.895
NetEase_Pl	ayLyrics	13	1	1	0	0.995	0.796
NetEase_	Comments	13	1	1	0	0.332	0.298
	ify_Main	13	3	0.44	1	0.83	0.698
	PlayList	13	2	0.51	1	0.828	0.613
Results saved (yolov5) [xiar			\$				

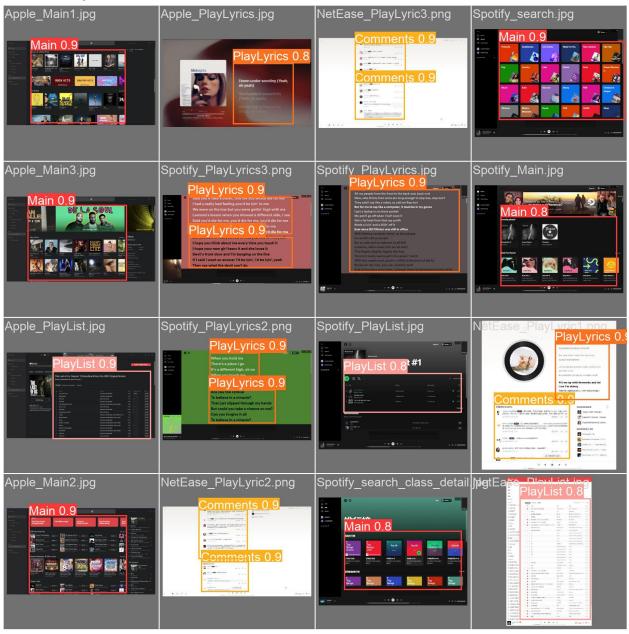
- Above is the first version of the yolov5 model, I put too many labels in this version. And the performance was bad, only 75% acc, and it will have bad result in the real classification task.
- In the second version I re-labeled the data into 4 classes and added some extra samples, the result was good.(99% acc)

500/500	3.6G	0.03126	0.01943	0.006795	9	640:	100%	3/3 [00:00	<pre>k00:00, 11.53it/s]</pre>	
	Class	Images	Instances	P	R	mAP50	mAP50-95:	100%	2/2 [00:00<00:00.	15.21it/s]
	all	18	25	0.985	1	0.995	0.891			
501 epochs comp	leted in 0	.205 hour	s.							
Optimizer strip				hts/last.pt, 4	42.1MB					
Optimizer strip										
Validating runs	/train/exp	017/weight	s/best.pt							
Fusing layers										
YOLOv5m summary		ers, 20865	057 paramete	ers, 0 gradier	nts, 47.9 G	LOPs				
	Class	Images	Instances	P	R	mAP50	mAP50-95:	100%	2/2 [00:00<00:00,	11.50it/s]
	all	18	25	0.986	1	0.995	0.902			-
	Main	18	8	0.992	1	0.995	0.93			
P	layList	18	3	0.984	1	0.995	0.895			
Pla	yLyrics	18	8	0.987	1	0.995	0.91			
c	omments	18	6	0.98	1	0.995	0.874			
Results saved t	o runs/tra	ain/exp17								
[xiangyj@node00	55 yolov5]	\$								
		-								

• The labels:



• The prediction result:



• Now I'm working on the video object detection and extraction of the bounding box into tabular data, and the eye tracking data extraction.

```
≣ videoDetect.py
                         \times
 1 import cv2
 2 import numpy as np
 3 from yolov5.yolov5 import YOLOv5
 4
 5 # Load the trained YOLO model
 6 model = YOLOv5(weights='yolov5s.pt', conf_thres=0.5, iou_thres=0.5)
 7
 8 # Read category labels
 9 with open('data.yaml', 'r') as f:
        data = yaml.load(f, Loader=yaml.FullLoader)
10
11 classes = data['names']
12
13 # Open video stream
14 # cap = cv2.VideoCapture(0) # Use the default camera
15 cap = cv2.VideoCapture('/home/ //yolov5/paperdata/video.mp4')
16 while True:
17
        ret, frame = cap.read()
18
        if not ret:
19
           break
20
21
       # Perform target detection
       results = model.detect(frame)
22
23
24
       # Draw bounding boxes and category labels
25
        for result in results:
           x1, y1, x2, y2, conf, cls = result
26
27
           cls_name = classes[int(cls)]
28
          cv2.rectangle(frame, (x1, y1), (x2, y2), (0, 255, 0), 2)
          cv2.putText(frame, cls_name, (x1, y1), cv2.FONT_HERSHEY_SIMPLEX, 1, (0, 255, 0), 2)
29
30
           #todo: output the bouding boxex labels data into csv files.
31
32
       # Display the processed frames
33
        cv2.imshow('frame', frame)
34
        if cv2.waitKey(1) == ord('q'):
35
           break
36
37 # Release resources
38 cap.release()
39 cv2.destroyAllWindows()
```

Video Detection worked

With the set of the

Fusing layers
YOLOv5m summary: 212 layers, 20865057 parameters, 0 gradients, 47.9 GFLOPs
video 1/1 (1/2105) /hc yolov5/paper data/Videos/Apple 02Video.mp4: 416x640 (no detections), 103.3ms
video 1/1 (2/2105) /hc video 1/2 (2/2100) /hc video 1/2 (2/2105) /hc
video 1/1 (3/2105) /hc you want yolov5/paper data/Videos/Apple 02Video.mp4: 416x640 (no detections), 67.2ms
video 1/1 (4/2105) /hc video a video vi
video 1/1 (5/2105) /hc
video 1/1 (6/2105) /hc yolov5/paper_data/Videos/Apple_02Video.mp4: 416x640 (no detections), 62.7ms
video 1/1 (7/2105) /hc
video 1/1 (8/2105) /hc yolov5/paper data/Videos/Apple 02Video.mp4: 416x640 (no detections), 63.3ms
video 1/1 (9/2105) /hc yolov5/paper data/Videos/Apple 02Video.mp4: 416x640 (no detections), 62.2ms
video 1/1 (10/2105) /here and yolov5/paper_data/Videos/Apple 02Video.mp4: 416x640 (no detections), 61.3ms
video 1/1 (11/2105) /h a state video vi
video 1/1 (12/2105) /h // // // // // // // /// //////////
video 1/1 (13/2105) /k // // // // // // // // // // // //
video 1/1 (14/2105) /h // // // // // // // // // // // //
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The speed is about 15 frames per second.

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Apple 02Video 1019.... 8 davs ado Here is the detection result, each class of label in each frame and the position.

For the Eye-tracking part, I have tested and output the Eye-tracking data with GazePoint Analysis.

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For the result analysis part:

The Video Frame and the EyeTracking are not in the same frequency(24FPS and 60Hz), and the timeline does not match, and the timing and location of the samples are subject to error. To address these issues, two possible solutions were proposed. The first solution is to use the KNN method with K = 3 and 5 to smooth the distribution of the video object position data and eye tracking fixation data respectively. This approach can help to reduce the noise and errors in the data and improve the accuracy of the analysis. The second solution is to use a time-based comparison method to measure the position of the object for each time segment. This method can help to compensate for the timing and location errors caused by the differences in the frequency of the Video Frame and the EyeTracking.

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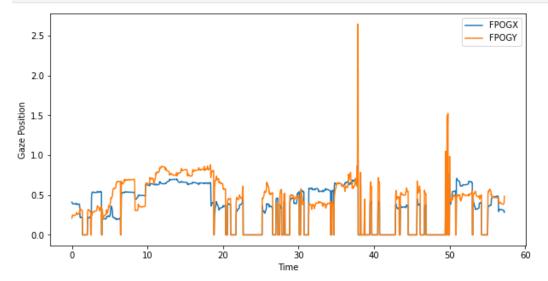
Eye Tracking data analysis

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	MED	IA_ID	MEDIA_NAME	CNT	TIME(2023/04/24	19:08:39.611)	TIMETICK(f=10000000)	FPOGX	FPOGY	FPOGS	FPOGD	FPOGID	. тті	0 TT	11 Т	TLV	PIXS	PIXV	AOI	SACCADE_MAG SACCA	DE_DIR	VID_FRAME	Unnamed: 51
0		0	NewMedia0	0		0.00000	544366653480				0.00000	1 .		1			0.0		NaN	0.0	0.0		
1		0	NewMedia0	1		0.01652	544366818723				0.01652					0			NaN	0.0	0.0		
2		0	NewMedia0	2		0.03286	544366982070 544367148372				0.03286					0			NaN NaN	0.0	0.0		
3		0	NewMedia0	3		0.06588	544367312254				0.04949					0			NaN	0.0	0.0		
	ows ×	52 col		-		0.00500	544501512254	0.55540	0.23700	0.0	0.00000		-		÷.	Ū	0.0	Ū		0.0	0.0	Ŭ	1011
x- Y-	Data Data	aset.il		5:FP	OGX, 11 BPOGX OGY, 12 BPOGY																		
34	180 181 182 183 184	57.17 57.18 57.20 57.21 57.23	3732 3366 1998																				

Original data

data preview & pre-process

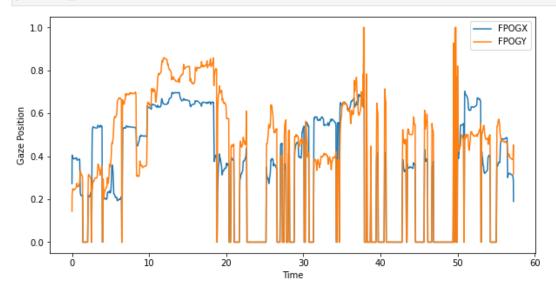
```
#]: # create line plot
import matplotlib.pyplot as plt
fig, ax = plt.subplots(figsize=(10,5))
ax.plot(times, X, label='FPOGX')
ax.plot(times, Y, label='FPOGY')
ax.legend()
ax.set_xlabel('Time')
ax.set_ylabel('Gaze Position')
plt.savefig(FileName+'Gazedata_kernel1.pdf',bbox_inches = 'tight', format='pdf')
plt.show()
```



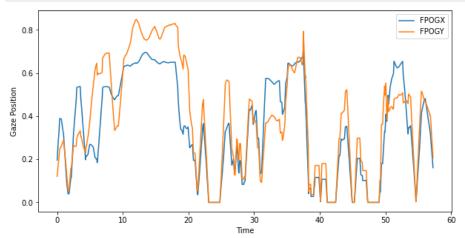
Filtered data

difference kernel size(3 and 50)

```
[5]: # Define the convolution kernel
     kernel = np.ones((3,))/3
     # Convolve the X and Y data with the kernel
     X_conv = np.convolve(X, kernel, mode='same')
     Y_conv = np.convolve(Y, kernel, mode='same')
     # Apply thresholding
     X_conv[X_conv > 1] = 1
     Y_conv[Y_conv > 1] = 1
     fig, ax = plt.subplots(figsize=(10,5))
     ax.plot(times, X_conv, label='FPOGX')
     ax.plot(times, Y_conv, label='FPOGY')
     ax.legend()
     ax.set_xlabel('Time')
     ax.set ylabel('Gaze Position')
     plt.savefig(FileName+'Gazedata_kernel'+str(len(kernel))+'.pdf',bbox_inches = 'tight', format='p
     plt.show()
```



```
[6]: # Define the convolution kernel
     kernel = np.ones((50,))/50
     # Convolve the X and Y data with the kernel
     X_conv1 = np.convolve(X, kernel, mode='same')
     Y_conv1 = np.convolve(Y, kernel, mode='same')
     # Apply thresholding
     X_conv1[X_conv1 > 1] = 1
     Y_conv1[Y_conv1 > 1] = 1
     fig, ax = plt.subplots(figsize=(10,5))
     ax.plot(times, X_conv1, label='FPOGX')
     ax.plot(times, Y_conv1, label='FPOGY')
     ax.legend()
     ax.set_xlabel('Time')
     ax.set_ylabel('Gaze Position')
     plt.savefig(FileName+'Gazedata_kernel'+str(len(kernel))+'.pdf',bbox_inches = 'tight', format='pdf')
     plt.show()
```



Load the txt files into data frame Load Frame Data

```
•[7]: #read files from folder, the files are named as 'Name0001.txt' to 'Name0100.txt'
      #the files are in the same folder as this script
      #the files are in the VOC format
      import os
      import glob
      import pandas as pd
      import xml.etree.ElementTree as ET
      def txt_to_dataframe(path):
         txt_list = []
          file_list = []
          for txt_file in glob.glob(path + '/*.txt'):
             # print(txt_file)
             with open(txt_file, 'r') as f:
                  # txt_list.append({txt_file:f.read()})
                  txt_list.append(f.read())
                  file_list.append(txt_file)
          # for loop to add the files into a dataframe and split the columns into multiple columns
          txt_df = pd.DataFrame(txt_list)
          all_data = pd.DataFrame()
          i = 0
          for txt in txt_list[:]:
             # print(txt)
             txt = txt.split('\n')
              txt = [x for x in txt if x]
             txt = [x.split(' ') for x in txt]
             df = pd.DataFrame(txt,columns = ['class','x','y','w','h'])
             # print(df)
             df['frame'] = file_list[i].split('/')[-1].split('_')[1].split('.')[0]
             # string to int
             df['frame'] = df['frame'].astype(int)
             all_data = all_data.append(df)
             i = i+1
          all_data = all_data.sort_values(by=['frame'])
          return txt_df,all_data
```

```
        class
        x
        y
        w
        h
        frame

        0
        0
        0.55365
        0.443773
        0.695796
        0.727695
        1707

        0
        0
        0.55365
        0.443773
        0.695796
        0.727695
        1708

        0
        0
        0.55365
        0.443773
        0.695796
        0.727695
        1709

        0
        0
        0.55365
        0.443773
        0.695796
        0.727695
        1710

        0
        0
        0.55365
        0.443773
        0.695796
        0.727695
        1710
```

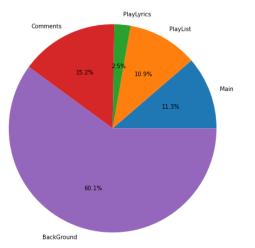
Match the object in txt and gaze data

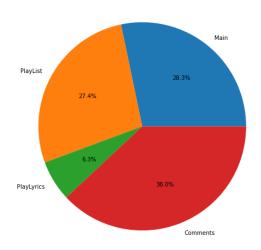
Measure the Object

```
[9]: fps = frames/times.iloc[-1]#30
      classes = pd.DataFrame()
      i = 0
      # for i in np.arange(len(X_conv)):
      for time in times[:-1]:
         # time = times[i]
         frame = int(time * fps)+1
         # frame = 1495
         # print(frame)
         lists = alldata[alldata['frame'] == frame]
         for num in range(len(lists)):
             item1 = lists.iloc[num]
             x,y,w,h = float(item1['x']),float(item1['y']),float(item1['w']),float(item1['h'])
             x0 = x - 0.5 * w - 0.05
             x1 = x+0.5*w +0.05
             y0 = y-0.5*h -0.05
             y1 = y+0.5*h +0.05
             # print(X[i],Y[i])
             # print(x0,x1,y0,y1)
             if X_conv[i]>=x0 and X_conv[i]<=x1 and Y_conv[i]>=y0 and Y_conv[i]<=y1:</pre>
                  cla = pd.DataFrame({'frame':[frame],'class':[item1['class']]})
              else:
                 cla = pd.DataFrame({'frame':[frame],'class':[4]})
             classes = pd.concat([classes, cla], axis=0)
          i = i+1
      print(classes)
          frame class
      0
            1 1
      0
             1
                   1
      0
            1
                  1
      0
             2
                  1
            2
      0
                  1
            ...
      . .
                 ...
          1709
      0
                  0
                 0
      0
          1710
      0
          1710
                   0
          1711
      0
                 0
      0
         1711
                   0
      [3567 rows x 2 columns]
[10]: values = classes['class'].astype(int).to_numpy()
      print(values)
      [1 1 1 ... 0 0 0]
```

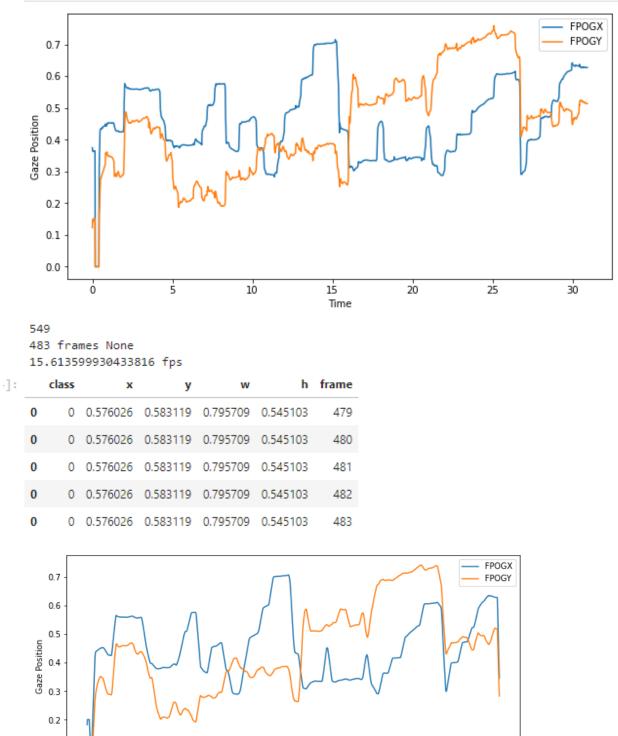
Result analysis

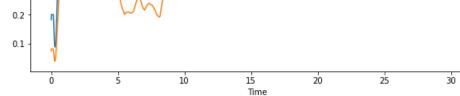






Dataset2 and smoothed Dataset2





1884 1884

Dataset2 result analysis

